

# Tentamen Voortgezette Mechanica

NS-350B, Blok 2, Retake Exam, April 20, 2017

Mark on *each* sheet clearly your name and collegekaartnummer.

Please use a **separate sheet** for each problem.

Read all questions and start with the one you find the easiest. Do not use too much time on any one question!

## 1 Hamiltonian

A mass  $m$  is connected to a moving piston by a horizontal spring with spring constant  $k$  and relaxed length  $l_0$ . The piston is arranged to move back and forth with position  $X_{\text{wall}} = A \sin \omega t$ . Let  $z$  measure the extension of the spring from its equilibrium length. (total: 20 points)

- Determine the Hamiltonian  $\mathcal{H}$  in terms of  $z$  and its conjugate momentum (*Hint: take the location of the piston at  $t=0$  as origin of your coordinate system*) (6 points)
- Write down Hamilton's equations. (5 points)
- Is  $\mathcal{H}$  the total energy? (discuss the general case and then refer to this particular problem) (3 points)
- Is  $\mathcal{H}$  conserved? (discuss the general case and then refer to this particular problem) (3 points)
- Is the total energy conserved? (3 points)

## 2 Fictitiously Down-Under

Qantas flight QF575 flies from Sydney, New South Wales, Australia, to Perth, Western Australia. The plane moves with constant speed  $v$  and at constant height  $h$  in a westerly direction (latitude  $35^\circ$  south). (total: 25 points)



- Make a sketch of all forces – real and fictitious – acting upon the plane on its way to Perth. Indicate the direction of the angular velocity of earth  $\vec{\Omega}$ . *N.B. : As you surely know, Australia is in the southern hemisphere!* (4 points)
- We now move to a coordinate system in which  $z$  points up (defined as opposing the force of gravity acting on the plane at rest),  $x$  points to the north, and  $y$  to the west. Calculate the components of the coriolis force in these coordinates. (8 points)

Shortly after take-off, the plane has to be re-routed to Melbourne due to an unexpectedly strong storm; the plane now flies with the same speed  $v$  and height  $h$ , but in a south-westerly direction.

- c) Make a sketch of all fictitious forces acting on the plane on its new course. Use the coordinates introduced in part b. [Hint:  $(\vec{a} + \vec{b}) \times \vec{c} = \vec{a} \times \vec{c} + \vec{b} \times \vec{c}$ ] (4 points)
- d) A travelling physicist has put up a bob (a weight on a string) in the plane. This bob, hanging from the ceiling of the economy class cabin, oscillates around a zero-position (with  $-\vec{z}_0$  pointing downwards) with a period  $T_0$ . Both zero-position and period were determined while the plane was standing still in Sydney. Explain whether and how these two parameters would change if:
- earth was not rotating at all? (2 points)
  - the plane follows its original course towards the west? (3 points)
  - the plane follows its new course towards the south-west? (3 points)

The airplane was slightly damaged in the storm and is grounded for repairs in Melbourne. Meanwhile, the bob continues to oscillate like a pendulum (ignore the friction). Slowly the plane in which it oscillates changes.

- What is the name of this type of pendulum, and in which direction does the plane of oscillation turn? (3 points)

### 3 Kepler Orbits of Higher Order Potentials

Consider two particles (reduced mass  $\mu$ ) orbiting each other under a central force with potential energy  $U(r) = kr^n$  with  $kn > 0$ . (total: 25 points)

- Explain what the condition  $kn > 0$  tells us about the nature of the force. (3 points)
- With given angular momentum  $\ell$ , sketch the effective potential energy  $U_{\text{eff}}$  for the cases  $n = 2, -1$  and  $-3$ ; make sure to sketch each term of the potential as well as the total potential, and indicate whether the potential has an extremum. (3+3+3 points)
- Find the radius at which the particle (with given angular momentum  $\ell$ ) can orbit at a fixed radius. For which value of  $n$  is this circular orbit stable (do your sketches confirm this conclusion)? (3+2 points)
- For the stable case show that the period of small oscillations about the circular orbit is  $\tau_{\text{osc}} = \tau_{\text{orb}}/\sqrt{n+2}$ . (4 points)
- Argue that if  $\sqrt{n+2}$  is a rational number then these orbits are closed. (4 points)

## 4 Tumbling Rotations

In this question, we will deal with the rotation of rigid bodies in three dimensions. Take a rectangular box of mass  $M$  and homogeneous density  $\rho$ . As shown in the figure on the right, the box has dimensions  $h < b < l$  and is rotating around a point along one of its shortest edges. (total: 20 points)

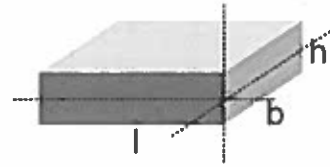


Figure 1: Rectangular Prism with homogeneous mass distribution. The origin is in the centre of one of the four shortest edges.

- (a) Calculate the inertial tensor  $I$  around the given axes and origin. (6 points)
- (b) The inertial tensor consists of *moments of inertia* and *products of inertia*. Explain these two terms and give the physical meaning of the two elements of the inertial tensor  $I_{zy}$  and  $I_{yz}$  for a rotation  $\vec{\omega}$  around an arbitrary axis. Argue from symmetry whether one of those two elements has to always be larger than the other. (3 points)
- (c) Around which of the three axes given in the figure can the body only rotate if there is an external torque? Give an explanation why this is so. (3 points)
- (d) Are any of the axes given in the figure *principal axes* of the body? Start by explaining what a “principal axis” is! (2 points)

Let us now consider rotations of the body occurring without an external torque (free rotations):

- (e) Through which point (origin) do we find the principal axes which correspond to the smallest *principal moments*  $\lambda_i$ ? What is a “principal moment” and which direction will the principal axes have in this case? (3 points)

## Useful Formulas

$$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta \quad \sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$$

$$\cos(\arcsin(\gamma)) = \sqrt{1 - \gamma^2} \quad \cos(\pi + \alpha) = -\cos \alpha \quad \sin(\pi + \beta) = -\sin \beta$$

$$\cos \alpha \cos \beta = \frac{1}{2}(\cos(\alpha + \beta) + \cos(\alpha - \beta)) \quad \sin \alpha \sin \beta = \frac{1}{2}(\cos(\alpha - \beta) - \cos(\alpha + \beta))$$

$$\sin^2 \alpha + \cos^2 \alpha = -e^{i\pi} = 1, \quad T_0 \approx 2\pi \sqrt{\frac{\ell}{g}}$$

$$c = \frac{\ell^2}{\gamma \mu} \quad E = \frac{\gamma^2 \mu}{2\ell^2} (\epsilon^2 - 1) \quad \mu = \frac{m_1 m_2}{m_1 + m_2} \quad \frac{c_1}{1 + \epsilon_1 \cos(\phi + \delta_1)} = \frac{c_2}{1 + \epsilon_2 \cos(\phi + \delta_2)}$$

$$U_{\text{cf}}(r) = \frac{\ell^2}{2\mu r^2} \quad \mathcal{L}_{\text{rel}} = \frac{1}{2}\mu \dot{r}^2 - U(r) \quad J_{ij} = I_{ij}^{\text{cm}} + m(\|\vec{a}\|^2 \delta_{ij} - a_i a_j)$$

$$\mathbf{I} = \iiint dV \rho(x, y, z) \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -yx & x^2 + z^2 & -yz \\ -zx & -zy & x^2 + y^2 \end{pmatrix}$$

$$\text{sphere: } I_{zz} = \frac{2}{5}mr^2 \quad \text{cylinder: } I_{zz} = \frac{1}{2}mr^2 \quad \text{hoop: } I_{zz} = mr^2$$

$$\left(\frac{dQ}{dt}\right)_{S_0} = \dot{Q} + \Omega \times Q \quad \left(\frac{d^2Q}{dt^2}\right)_{S_0} = \ddot{Q} + 2\Omega \times \dot{Q} + \Omega \times (\Omega \times Q)$$

$$\mathcal{L} = T - V \quad \frac{\partial \mathcal{L}(q(t), \dot{q}(t), t)}{\partial q} - \frac{d}{dt} \frac{\partial \mathcal{L}(q(t), \dot{q}(t), t)}{\partial \dot{q}} = 0$$

$$\mathcal{H} = \sum p_i \dot{q}_i - \mathcal{L} = T + U \quad \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q_i} \quad \dot{q}_i = \frac{\partial \mathcal{H}}{\partial p_i}$$

$$\vec{L} = (\lambda_1 \omega_1, \lambda_2 \omega_2, \lambda_3 \omega_3) \quad \dot{\vec{L}} + \vec{\omega} \times \vec{L} = \vec{\Gamma}$$

$$\lambda \vec{\omega} = \mathbf{I} \vec{\omega} \quad (\mathbf{I} - \lambda \mathbf{E}_3) \vec{\omega} = 0 \quad \det(\mathbf{I} - \lambda \mathbf{E}_3) = 0 \quad \mathbf{E}_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$F_i(d\vec{A}) = \sum_j \sigma_{ij} dA_j \quad \vec{F}(d\vec{A}) = \Sigma d\vec{A} = \Sigma \hat{n} dA$$

For a surface and a point on that surface:  $S(x, y, z) = 0$ ,  $P \in S$ :  $\vec{n} = \nabla S$

$$\int_0^{2\pi} \sin^n(x) \cos^m(x) dx = 0 \text{ for odd } m \text{ or } n.$$

$$\int_0^{2\pi} \cos^2(x) dx = \int_0^{2\pi} \sin^2(x) dx = \pi$$

$$\arctan 0 = 0 \quad \arctan \pm \infty = \pm \frac{1}{2}\pi \quad \det(\mathbf{K} - \omega^2 \mathbf{M}) = 0$$

$$\sin 35^\circ = 0.574 \quad \cos 35^\circ = 0.819 \quad \tan 35^\circ = 0.700$$

$$f(x^*) = x^* \quad f(x_a) = x_b \wedge f(x_b) = x_a \Rightarrow f(f(x^*)) = x^* \quad x_t = x^* + \epsilon \Rightarrow \epsilon_{t+1} \approx f'(x^*) \epsilon_t$$